

1.2 Gaussian, Row Reduction and Echelon Forms

$$\begin{array}{rcl} x + 2y + z & = & 3 \\ 3x + 6y - z & = & 4 \\ 5x + 10y + z & = & 10 \end{array} \leftrightarrow \begin{bmatrix} 1 & 2 & 1 & 3 \\ 3 & 6 & -1 & 4 \\ 5 & 10 & 1 & 10 \end{bmatrix}$$

Elementary Row Operations

replacement

interchange

scaling

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Elementary Row Operations

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Strict Gaussian Elimination

1. When possible, use top left spot in row 1 to eliminate the other column 1 terms via replacement
2. Ignore row 1 and use first nonzero spot in row 2 to eliminate the terms below it via replacement
3. ... triangular (interchange as needed)

Leading Entries, Pivots and Pivot Columns

$$\begin{array}{rcl} x + 2y + z & = & 3 \\ 3x + 6y - z & = & 4 \\ 5x + 10y + z & = & 10 \end{array} \quad \left[\begin{array}{cccc} 1 & 2 & 1 & 3 \\ 3 & 6 & -1 & 4 \\ 5 & 10 & 1 & 10 \end{array} \right] \begin{array}{l} \\ \xrightarrow{r'_2 = -3r_1 + r_2} \\ \xrightarrow{r'_3 = -5r_1 + r_3} \end{array}$$

$$\left[\begin{array}{cccc} 1 & 2 & 1 & 3 \\ -3 \cdot 1 + 3 = 0 & -3 \cdot 2 + 6 = 0 & -3 \cdot 1 - 1 = -4 & -3 \cdot 3 + 4 = -5 \\ -5 & 10 & 1 & 10 \end{array} \right]$$
$$\left[\begin{array}{cccc} 1 & 2 & 1 & 3 \\ 0 & 0 & -4 & -5 \\ -5 \cdot 1 - 5 = 0 & -5 \cdot 2 + 10 = 0 & -5 \cdot 1 + 1 = -4 & -5 \cdot 3 + 10 = -5 \end{array} \right]$$

We used the 1, a *leading nonzero entry* across row 1 to create 0s below it. It's spot is a *pivot position*. A *pivot column* is a corresponding column in original matrix. 1 is a *pivot* for x .

Leading Entries, Pivots and Pivot Columns

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$$\left[\begin{array}{cccc} 1 & 2 & 1 & 3 \\ 0 & 0 & -4 & -5 \\ -5 \cdot 1 - 5 = 0 & -5 \cdot 2 + 10 = 0 & -5 \cdot 1 + 1 = -4 & -5 \cdot 3 + 10 = -5 \end{array} \right]$$

We used the 1, a *leading nonzero entry* across row 1 to create 0s below it. It's spot is a *pivot position*. A *pivot column* is a corresponding column in original matrix. 1 is a *pivot* for x .

$$\left[\begin{array}{cccc} \textcircled{1} & 2 & 1 & 3 \\ 0 & 0 & \textcircled{-4} & -5 \\ 0 & 0 & -4 & -5 \end{array} \right] \left[\begin{array}{cccc} 1 & 2 & 1 & 3 \\ 3 & 6 & -1 & 4 \\ 5 & 10 & 1 & 10 \end{array} \right]$$

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$$\left[\begin{array}{cccc} 1 & 2 & 1 & 3 \\ 0 & 0 & -4 & -5 \\ 0 & 0 & -4 & -5 \end{array} \right] \xrightarrow{r'_3 = -r_2 + r_3}$$

$$\left[\begin{array}{cccc} 1 & 2 & 1 & 3 \\ 0 & 0 & -4 & -5 \\ -1 \cdot 0 + 0 = 0 & -1 \cdot 0 + 0 = 0 & -1 \cdot -4 - 4 = 0 & -1 \cdot -5 - 5 = 0 \end{array} \right]$$

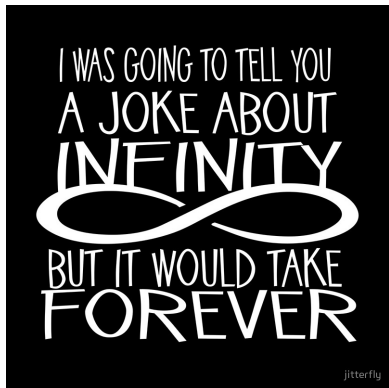
$$\left[\begin{array}{cccc} \textcircled{1} & 2 & 1 & 3 \\ 0 & 0 & \textcircled{-4} & -5 \\ 0 & 0 & 0 & 0 \end{array} \right] \text{ row echelon form, pivots circled, 0s below}$$

Free Parameters

$$\begin{bmatrix} 1 & 2 & 1 & 3 \\ 3 & 6 & -1 & 4 \\ 5 & 10 & 1 & 10 \end{bmatrix} \longrightarrow \begin{bmatrix} \textcircled{1} & 2 & 1 & 3 \\ 0 & 0 & \textcircled{-4} & -5 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

- once in row echelon form, check for consistency
- if consistent, then identify pivots & free parameters, if any:
no pivot in 2nd column, so y is a *free parameter*: $y = t$.
- back substitute variables attached to pivots, working from bottom up.
 - row 3: $[0 \ 0 \ 0 \ 0]$ represents $0x + 0y + 0z = 0$ no info
 - row 2: $[0 \ 0 \ -4 \ -5]$ represents $0x + 0y - 4z = -5$, so $z = \frac{5}{4}$
 - row 1: $[1 \ 2 \ 1 \ 3]$ represents $x + 2y + z = 3$, so
 $x = 3 - 2y - z = 3 - 2t - \frac{5}{4} = \frac{7}{4} - 2t$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \frac{7}{4} - 2t \\ t \\ \frac{5}{4} \end{pmatrix}$$



$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \frac{7}{4} - 2t \\ t \\ \frac{5}{4} \end{pmatrix}$$

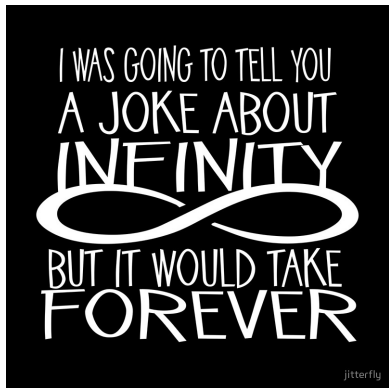
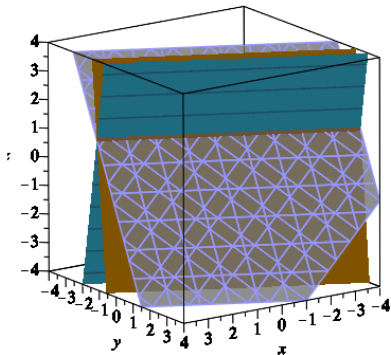


Image Credit: jitterfly



<https://www.redbubble.com/people/jitterfly/works/26106035?p=canvas-print&rel=carousel>

Row Echelon Form

A matrix is in *row echelon form* (ref) if

1. all nonzero rows are above any rows of all zeros
2. each leading entry of a row is in a column to the right of the leading entry of the row above it
3. all entries in a column below a leading entry are zeros

Maple: `GaussianElimination(A)`

ref solutions

Which augmented matrix is not in ref/Gaussian form?

a)
$$\begin{bmatrix} 3 & 2 & 5 & 6 & 11 \\ 0 & 0 & 2 & -5 & 7 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}$$

c)
$$\begin{bmatrix} 1 & 2 & -2 & 3 \\ 0 & 4 & 8 & 4 \\ 0 & 0 & 2 & -4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

b)
$$\begin{bmatrix} 3 & 2 & 5 & 6 & 11 \\ 0 & 0 & 2 & 0 & 7 \\ 0 & 0 & 4 & 0 & 14 \end{bmatrix}$$

ref solutions

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b)
$$\begin{bmatrix} 3 & 2 & 5 & 6 & 11 \\ 0 & 0 & 2 & 0 & 7 \\ 0 & 0 & 4 & 0 & 14 \end{bmatrix}$$

consider how many solutions, if any, and consider how many free variables, if any

$$a) \begin{bmatrix} 3 & 2 & 5 & 6 & 11 \\ 0 & 0 & 2 & -5 & 7 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix} \quad c)$$

no solution, no concurrent intersections in \mathbb{R}^4

$$\begin{bmatrix} 1 & 2 & -2 & 3 \\ 0 & 4 & 8 & 4 \\ 0 & 0 & 2 & -4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

unique solution, a point in \mathbb{R}^3

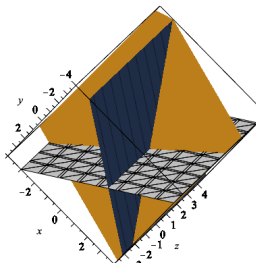
$$b) \begin{bmatrix} 3 & 2 & 5 & 6 & 11 \\ 0 & 0 & 2 & 0 & 7 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

infinitely many solutions, a plane in \mathbb{R}^4

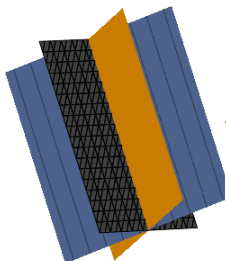
underdetermined versus overdetermined

Solutions and Pivots

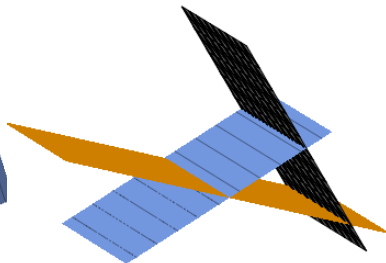
3 equations and 3 unknowns. How many pivot positions and pivot columns does each augmented matrix have?



1 solution
corner of room



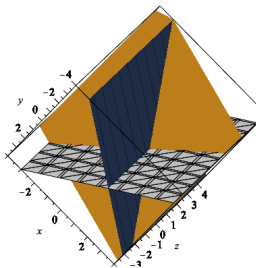
infinite solutions
book spine



0 solutions
hands + table

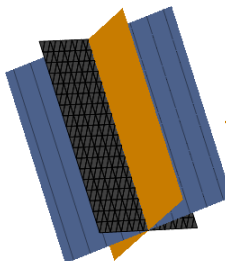
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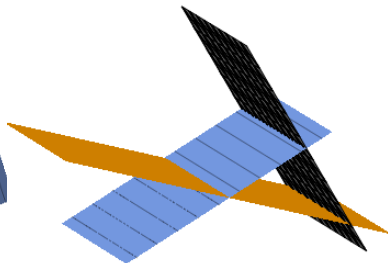
1 solution
corner of room

3 pivots



infinite solutions
book spine

2 pivots



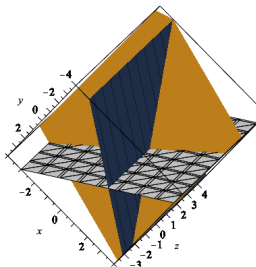
0 solutions
hands + table

at least 1 pivot in =

any linear system has 0, 1, ∞ solutions

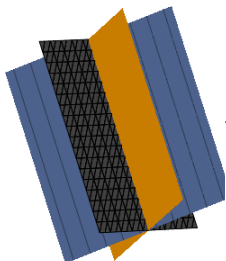
Solutions and Pivots

3 equations and 3 unknowns. How many pivot positions and pivot columns does each augmented matrix have?



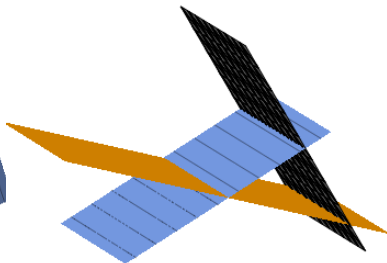
1 solution
corner of room

3 pivots



infinite solutions
book spine

2 pivots



0 solutions
hands + table

at least 1 pivot in =

any linear system has 0, 1, ∞ solutions : think of pivots!
geometry!

can an underdetermined system ever have 1 solution?

Reduced Row Echelon Form

A matrix is in *reduced row echelon form* (rref) if

1. all nonzero rows are above any rows of all zeros
2. each leading entry of a row is in a column to the right of the leading entry of the row above it
3. all entries in a column below a leading entry are zeros.
4. **the leading entry in each nonzero row is a 1**
5. **each leading 1 is the only nonzero entry in its column.**

Gauss-Jordan elimination

Maple: `ReducedRowEchelonForm(A)`

Moving from Gaussian to Reduced Row Echelon Form

$$\begin{bmatrix} 1 & 2 & -2 & 3 \\ 0 & 4 & 8 & 4 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 2 & -2 & 3 \\ 0 & 4 & 8 & 4 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\xrightarrow{r'_2 = \frac{1}{4}r_2}$$

$$\begin{bmatrix} 1 & 2 & -2 & 3 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Moving from Gaussian to Reduced Row Echelon Form

$$\begin{bmatrix} 1 & 2 & -2 & 3 \\ 0 & 4 & 8 & 4 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\xrightarrow{r'_2 = \frac{1}{4}r_2}$$

$$\begin{bmatrix} 1 & 2 & -2 & 3 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\xrightarrow{r'_1 = -2r_2 + r_1}$$

$$\begin{bmatrix} 1 & 0 & -6 & 1 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Moving from Gaussian to Reduced Row Echelon Form

$$\begin{bmatrix} 1 & 2 & -2 & 3 \\ 0 & 4 & 8 & 4 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{r'_3 = \frac{1}{2}r_3} \begin{bmatrix} 1 & 0 & -6 & 1 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$
$$\begin{matrix} r'_2 = -2r_3 + r_2 \\ r'_1 = 6r_3 + r_1 \end{matrix} \xrightarrow{\hspace{1cm}} \begin{matrix} x & y & z & = \\ \textcircled{1} & 0 & 0 & 13 \\ 0 & \textcircled{1} & 0 & -3 \\ 0 & 0 & \textcircled{1} & 2 \\ 0 & 0 & 0 & 0 \end{matrix}$$

no inconsistencies [0 0 0 nonzero] and full pivots so unique solution $(x, y, z) = (13, -3, 2)$

Flops

A flop, for floating point operation, is a measure of $+$, $-$, \times , \div

- For an $n \times (n + 1)$ matrix, it can take as many as $\frac{2n^3}{3} + \frac{n^2}{2} - \frac{7n}{6}$ flops to apply Gaussian elimination to reach the row echelon form (the *forward phase*).
- The *backwards phase* from row echelon form to reduced row echelon form (making use of all the zeros) can take another n^2 flops.

3×4 from ref to rref?

Describe the Algebra and Geometry of the Solutions

Describe the solution set to the *homogeneous* linear system with Gaussian Elimination(A)

$$\left[A \mid \begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right] \xrightarrow{\text{strict Gaussian}} \begin{array}{c} x_1 \quad x_2 \quad x_3 \quad x_4 \quad = \\ \left[\begin{array}{ccccc} 3 & 0 & -3 & 1 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \end{array}$$

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- check for consistency
- if consistent, identify free variables, if any, from variables missing pivots. Parameterically, $x_3 = s$ and $x_4 = t$. Geometrically, two free variables is a plane

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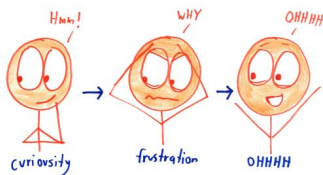
- check for consistency
- if consistent, identify free variables, if any, from variables missing pivots. Parameterically, $x_3 = s$ and $x_4 = t$. Geometrically, two free variables is a plane
- back substitute variables attached to pivots, working from bottom up
row 2 eq: $0x_1 + x_2 - x_3 + 0x_4 = 0$ so $x_2 = x_3 = s$
row 1 eq: $3x_1 = 3x_3 - x_4 = 3s - t$ so $x_1 = s - \frac{t}{3}$
- $(x_1, x_2, x_3, x_4) = (s - \frac{t}{3}, s, s, t)$ plane in \mathbb{R}^4

Use strict Gaussian on the following augmented matrix

$$\begin{bmatrix} 1 & 1 & 0 & 2 \\ 2 & 1 & 3 & 3 \\ 2 & 2 & h & 4 \end{bmatrix} ?$$

- a) it takes at least 3 elementary row operations to get to Gaussian here
- b) from Gaussian we can see that we have full pivots for all h
- c) from Gaussian we can see that some h give us no solutions and a missing pivot
- d) more than one of the above is true
- e) none of the above

The Mathematics Three-Step





<http://depts.washington.edu/womenctr/wordpress/wp-content/uploads/MC-Logo.png>