

<u>SUBSPACE, THE [O, cv & u+v] FRONTIER</u>





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nonempty set of vectors on which we can do + and scalar mult:

- $\vec{v}_1 + \vec{v}_2$ is in the space whenever the individual vectors are
- $c\vec{v}$ is in the space whenever \vec{v} is and c is a real scalar

$$t\begin{bmatrix}1\\1\end{bmatrix}$$
 versus $t\begin{bmatrix}1\\1\end{bmatrix} + \begin{bmatrix}1\\0\end{bmatrix}$

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- **0**
- line through $\vec{0}$
- \mathbb{R}^2

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What are the subspaces of \mathbb{R}^3 ?

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What are the subspaces of \mathbb{R}^3 ?

- Õ
- line through $\vec{0}$
- plane through 0
- R³

Basis for a Subspace

• a linearly independent spanning set like $\left\{ \begin{bmatrix} 1\\2\\3 \end{bmatrix} \right\}$ or $\left\{ \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} 4\\5\\6 \end{bmatrix} \right\}$ but not $\left\{ \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} 4\\5\\6 \end{bmatrix}, \begin{bmatrix} 7\\8\\9 \end{bmatrix} \right\}$

Basis for a Subspace

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- $\begin{vmatrix} 1 & 4 & 7 & 0 \\ 2 & 5 & 8 & 0 \\ 3 & 6 & 9 & 0 \end{vmatrix} \rightarrow \begin{vmatrix} 0 & 4 & 7 & 0 \\ 0 & 3 & -6 & 0 \\ 0 & 0 & 0 & 0 \end{vmatrix}$ missing a pivot for z
- span of a set of vectors is a subspace
- dimension



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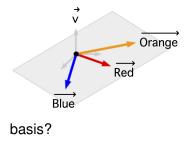
Difference Between a Basis and the Subspace Itself

• subspace is generated by the basis via all linear combinations, i.e. the span basis: $\left\{ \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} 4\\5\\6 \end{bmatrix} \right\}$ subspace: $s \begin{bmatrix} 1\\2\\3 \end{bmatrix} + t \begin{bmatrix} 4\\5\\6 \end{bmatrix}$

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exclusive club xy0-plane in ℝ³



- column space of A: span of the columns of A
- null space of *A* : set of solutions to $A\vec{x} = \vec{0}$

Two Special Subspaces Related to a Matrix • column space of *A*: span of the columns of *A* • null space of *A* : set of solutions to $A\vec{x} = \vec{0}$ $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 1 \end{bmatrix}$ pivot columns basis of the column space $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 1 \end{bmatrix} \xrightarrow{r'_2 = -r_1 + r_2} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & -1 & -3 \end{bmatrix}$ **Two Special Subspaces Related to a Matrix** • column space of *A*: span of the columns of *A* • null space of *A* : set of solutions to $A\vec{x} = \vec{0}$ $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 1 \end{bmatrix}$ pivot columns basis of the column space $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 1 \end{bmatrix}$ pivot columns basis of the column space $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 1 \end{bmatrix}$ $\xrightarrow{r'_2 = -r_1 + r_2}$ $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & -1 & -3 \end{bmatrix}$ $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \end{bmatrix} \right\}$ geometry of entire column space?

Two Special Subspaces Related to a Matrix column space of A: span of the columns of A • null space of A : set of solutions to $A\vec{x} = \vec{0}$ $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 1 \end{bmatrix}$ pivot columns basis of the column space $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 1 \end{bmatrix} \xrightarrow{r'_2 = -r_1 + r_2} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & -1 & -3 \end{bmatrix} \quad \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \end{bmatrix} \right\}$ geometry of entire column space? all of \mathbb{R}^2 null space write $A\vec{x} = \vec{0}$ solutions by parameterizing $\begin{bmatrix} 1 & 2 & 3 & 4 & 0 \\ 1 & 2 & 2 & 1 & 0 \end{bmatrix} \xrightarrow{r'_2 = -r_1 + r_2} \begin{bmatrix} 1 & 2 & 3 & 4 & 0 \\ 0 & 0 & (1) & -3 & 0 \end{bmatrix}$

Two Special Subspaces Related to a Matrix • column space of A: span of the columns of A • null space of A : set of solutions to $A\vec{x} = \vec{0}$ $A = \begin{vmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 1 \end{vmatrix}$ pivot columns basis of the column space $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 1 \end{bmatrix} \xrightarrow{r'_2 = -r_1 + r_2} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & -1 & -3 \end{bmatrix} \quad \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \end{bmatrix} \right\}$ geometry of entire column space? all of \mathbb{R}^2 null space write $A\vec{x} = \vec{0}$ solutions by parameterizing $\begin{bmatrix} 1 & 2 & 3 & 4 & 0 \\ 1 & 2 & 2 & 1 & 0 \end{bmatrix} \xrightarrow{r'_2 = -r_1 + r_2} \begin{bmatrix} 1 & 2 & 3 & 4 & 0 \\ 0 & 0 & (1) & -3 & 0 \end{bmatrix}$ back substitution $x_2 = s$, $x_4 = t$, row 2: [0 0 -1 -3 0] $x_3 = -3t$, row 1: $x_1 = -2x_2 - 3x_3 - 4x_4 = -2s - 3(-3t) - 4t = -2s + 5t$

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- column space of A: span of the columns of A
- null space of A: set of solutions to $A\vec{x} = \vec{0}$

$$A = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

- a) What is a basis for the column space of A?
- b) What is the column space of A?
- c) What is the geometry of the column space of A?

- column space of A: span of the columns of A
- null space of A: set of solutions to $A\vec{x} = \vec{0}$

$$A = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

a) What is a basis for the column space? $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$

b) What is the column space of A?

$$\begin{bmatrix} \begin{bmatrix} 0 \end{bmatrix} \begin{bmatrix} 0 \end{bmatrix} \begin{bmatrix} 1 \end{bmatrix} \end{bmatrix}$$
$$s \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + u \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

c) What is the geometry of the column space of A? infinite volume in ℝ³ is all of ℝ³

2.8

- column space of A: span of the columns of A
- null space of A: set of solutions to $A\vec{x} = \vec{0}$

$$A = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

d) What is the nullspace of A?

- e) What is a basis for the nullspace of A?
- f) What is the geometry of the nullspace of A?

- column space of A: span of the columns of A
- null space of A: set of solutions to $A\vec{x} = \vec{0}$
- d) What is the nullspace of A? Augment with 0 and

parameterize $[A0] = \begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & (1) & 1 & 0 & 0 \\ 0 & 0 & 0 & (1) & 0 \end{bmatrix}$ x_3 is free so $x_3 = t$. row 3: $[0 \ 0 \ 0 \ 1 \ 0] x_4 = 0$ row 2: [0 1 1 0 0] $x_2 + x_3 = 0$ so $x_2 = -x_3 = -t$ row 1: [1 0 0 1 0] $x_1 + x_4 = 0$ so $x_1 = -x_4 = -0 = 0$ nullspace is $\begin{bmatrix} 0\\-t\\t\\ 0 \end{bmatrix} = t \begin{vmatrix} 0\\-1\\1\\0 \end{vmatrix}$ e) basis is $\left\{ \begin{vmatrix} 0\\-1\\1\\0 \end{vmatrix} \right\}$ What is the geometry of the nullspace of A? line in \mathbb{R}^4

Applications

LIVING IN A NULLSPACE BY NULL THX FOR LUNCH TODAY MY MONEY GETS FOR A FRIEND IS LIKE PPED TO ZERO LIVING IN A NULLISPAC \odot 5) YOU MEAN EVERYDAY?

- A directions we can go based on thrusters
- A rate of return on investments
- A room illumination
- A set of map directions (vectors) at entrance to forest

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Null Space and Column Space Which of the following statements about are true about the

nullspace (or null space) and column space of $M = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$.

Note that *M* is row equivalent to $\begin{bmatrix} 1 & 4 \\ 0 & -3 \\ 0 & 0 \end{bmatrix}$ and when *M* is

augmented with a generic vector and reduced to Gaussian, the last row becomes $\begin{bmatrix} 0 & 0 & b_1 - 2b_2 + b_3 \end{bmatrix}$

- a) the column space is the plane $b_1 2b_2 + b_3 = 0$ in \mathbb{R}^3
- b) the column space is the plane $s \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} + t \begin{bmatrix} 4 \\ 5 \\ -1 \end{bmatrix}$ in \mathbb{R}^3
- c) the nullspace is $\vec{0}$ in \mathbb{R}^2
- d) all of the above
- e) two of the above

Maple's Null Space and Column Space Using with(LinearAlgebra): with(plots): M:=Matrix([[1,4],[2,5],[3,6]]); ColumnSpace(M); Maple outputs the equivalent of $\left\{ \begin{bmatrix} 1\\0\\-1 \end{bmatrix}, \begin{bmatrix} 0\\1\\2 \end{bmatrix} \right\}$. Are these vectors even in the column space? We can check $b_1 - 2b_2 + b_3 = 0$

Maple's Null Space and Column Space Using with (Linear Algebra): with (plots): M:=Matrix([[1,4],[2,5],[3,6]]); ColumnSpace(M); Maple outputs the equivalent of $\left\{ \begin{bmatrix} 1\\0\\-1 \end{bmatrix}, \begin{bmatrix} 0\\1\\2 \end{bmatrix} \right\}$. Are these vectors even in the column space? We can check $b_1 - 2b_2 + b_3 = 0$ Yes! For $\begin{bmatrix} 1\\0\\-1 \end{bmatrix} b_1 - 2b_2 + b_3 = 1 - 2(0) - 1 = 0$ For $\begin{vmatrix} 0 \\ 1 \\ 2 \end{vmatrix}$ $b_1 - 2b_2 + b_3 = 0 - 2(1) + 2 = 0$

basis with 1s and 0s in the first coordinates. Spans the same space, the same plane in \mathbb{R}^3 . It's a basis, not entire space.

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Null Space of a Non-Square Matrix The null space of a non-square matrix is a subspace of

- a) \mathbb{R} number of rows
- b) Rnumber of columns

c) further work must be done to tell

[HTML] The convex basis of the left null space of the stoichiometric matrix leads to the definition of metabolically meaningful pools I Famili, BO Palsson - Biophysical journal, 2003 - Elsevier

... between the reaction rate vectors, v, and time derivative of metabolite concentrations, dx/dt or

x'. Each two subspaces in the domain (ie, the null space and row space) and codomain (ie,

the left null space and column space) form orthogonal pairs with one another ...

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Closed-loop subspace identification using the parity space

J Wang, SJ Qin - Automatica, 2006 - Elsevier

... It is shown that the column space of the observability matrix extracted from SOPIM is equivalent to that from SIMPCA-Wc... (9), we have (11) $\lim N \to \infty 1 N (\Gamma f \perp) T [I - H f] Z f Z p T = 0$. Therefore, $(\Gamma f \perp) T [I - H f]$ is in the left null space of lim N $\rightarrow \infty (1/N) Z f Z p T$. If we ... ☆ 99 Cited by 92 Related articles All 6 versions

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C Cornwell, P Schmidt, RC Sickles - Journal of econometrics, 1990 - Elsevier

... Let PL, = Q(Q'Q>-IQ' be the projection onto the column space of Q and ML, = I - Pp be the projection onto the null space of Q. We derive three different estimators for (2.3), each of which is a straight- forward extension of an established procedure for the standard panel data ...

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Degrees of freedom of the MIMO Y channel: Signal space alignment for network codina

N Lee, JB Lim, J Chun - IEEE Transactions on Information ..., 2010 - ieeexplore.ieee.org ... designed to lie in the null space of channel matrix , ie ... Since all users have antennas and the relay equips antennas, there exists a -dimensional intersection subspace consti- tuted by the column space of channel matrices for each user pair. Let denote the ...

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