

Terms for Test 3

- 1. invertible
- 2. determinant of 2×2
- 3. determinant of 3×3 via 6 diagonals
- 4. determinant via Laplace expansion
- 5. span of v_1, v_2, \dots, v_k
- 6. v_1, v_2, \dots, v_k span \mathbb{R}^n
- 7. v_1, v_2, \dots, v_k linearly independent
- 8. subspace
- 9. basis for a subspace
- 10. column space of A
- 11. homogeneous equation
- 12. null space of A
- 13. eigenvalue
- 14. eigenvector
- 15. characteristic equation for eigenvalues
- 16. eigenspace and solving for a basis
- 17. eigenvector decomposition
- 18. trajectory
- 19. long term behavior (rate and direction/line)

Examples

- 1. determinant of 3×3 via the diagonal method
- 2. determinant of 3×3 by Laplace expansion
- 3. column space and null space of a matrix
- 4. a projection matrix and it's eigenvectors and eigenvalues
- 5. a reflection matrix and it's eigenvectors and eigenvalues
- 6. a shear matrix and it's eigenvectors and eigenvalues
- 7. a rotation matrix and it's eigenvectors and eigenvalues

Write out **definitions, big picture ideas, multiple representations and/or examples** (whatever you would find the most helpful) as we cover them, or as a review of previous material.

- 1. A is invertible if
- 2. determinant of 2×2
- 3. determinant of 3×3 via 6 diagonals
- 4. determinant via Laplace expansion
- 5. span of v_1, v_2, \dots, v_k
- 6. v_1, v_2, \dots, v_k span \mathbb{R}^n ?

7. v_1, v_2, \dots, v_k linearly independent

8. subspace

9. basis for a subspace

10. column space of A

11. homogeneous equation

12. null space of A

13. eigenvalue

14. eigenvector

15. characteristic equation for eigenvalues

16. eigenspace and solving for a basis

17. eigenvector decomposition

18. trajectory

19. long term behavior (rate and direction/line)

Write out *examples* for the following:

1. determinant of 3×3 via the diagonal method
2. determinant of 3×3 by Laplace expansion
3. column space and null space of a matrix
4. a projection matrix and it's eigenvectors and eigenvalues
5. a reflection matrix and it's eigenvectors and eigenvalues
6. a shear matrix and it's eigenvectors and eigenvalues
7. a rotation matrix and it's eigenvectors and eigenvalues