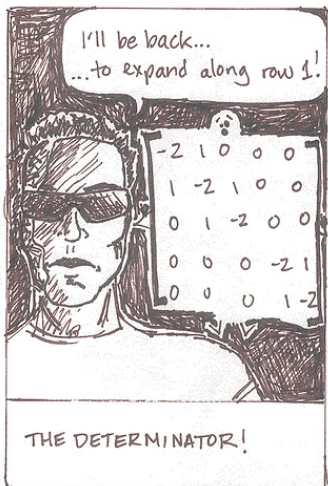


Test 3: + 2.8(146-150), 3.1(163-167), 3.2(169-172), 3.3(180-181), 5.1(265-269), 5.6(301-304) & apps

- Formatting same as prior tests. Test 3 is majority new material.
- hw, problem sets, & clicker questions [solutions online]
- computations, definitions, critical reasoning & “big picture”
- **1.1, 1.2 & 1.5**: Gaussian elimination, algebra and geometry of solutions of systems of equations...
- **1.4**: connects everything together
- **1.3 and 1.7**: algebra and geometry of vectors (linear combinations/mixing, span, li...)
- **2.1 and 2.2**: matrix algebra: $A + B$, cA , A^T , AB , $A_{2 \times 2}^{-1}$, $\det(A_{2 \times 2})$
- **2.3**: theorem 8: what makes a matrix invertible [connects 2.2 to 1.1, 1.2, 1.3 and 1.7] & condition #
- **1.8 (62, 65, 67-68), 1.9 (70-75), 2.7**: linear transformations
- **apps**: Hill cipher, computer graphics/animations, computer speed and reliability
- **3.1-3.3**: algebra and geometry of determinants, invertibility
- **2.8**: subspace, basis, column space and null space
- **5.1**: eigenvectors & eigenvalues alg & geom, nullspace($A - \lambda I$)
- **5.6**: eigenvector decomposition, limit, trajectory & populations

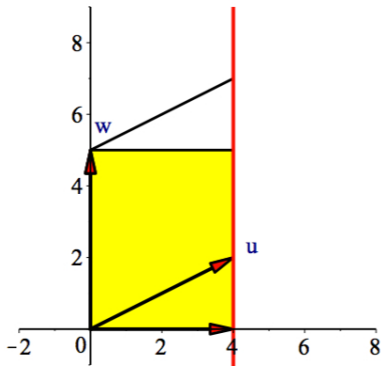


2007

@COURTNEY GIBBONS

$$-2 \cdot (-1)^{1+1} \begin{vmatrix} -2 & 1 & 0 & 0 \\ 1 & -2 & 0 & 0 \\ 0 & 0 & -2 & 1 \\ 0 & 0 & 1 & -2 \end{vmatrix} + 1 \cdot (-1)^{1+2} \begin{vmatrix} 1 & 1 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & -2 & 1 \\ 0 & 0 & 1 & -2 \end{vmatrix} + 0s$$





Replacement $r'_j = -3r_1 + r_j$ are shear matrices when written in elementary matrix form like $\begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix}$ or $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}$ —preserve the determinant (area, volume...) of a matrix and turns parallelograms and parallelepipeds formed by the vectors into rectangles and rectangular prisms

What Makes You Invertible

In **verse**

Music by One Direction & idea adapted from Art Benjamin
Interpreted by Dr. Sarah and Joel Landsberg

Baby you'll light up if one of these facts is so,
but you'll need n square columns and rows:

- Like when \mathbb{R}^n is the span of the matrix columns
- That's when you know oh-oh invertible!
- If always you uniquely solve $A\vec{x}$ is \vec{b}
- Or if your columns have no linear dependency
- Or if matrix reduces to identity

Not zero - no no

That makes it not invertible!

Shout out if one of these facts is so...

but you'll need n square columns and rows:

- Like when your matrix determinant's non-zero

Is when you know oh-oh—that makes it invertible!

Subspace: it's linear (linear combinations)

Subspace basis: span (full row pivots) + l.i. (full column pivots)

$$\text{reduced } A = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

column space of A =span of columns $[c_1 \vec{v}_1 + \dots]$ or equations like $b_1 - 2b_2 + b_3 = 0$ from $[A|\vec{b}]$ reduction.

A basis is {column 1, ... of original matrix} - they span the column space via linear combinations and are l.i.

null space of A =solutions of $A\vec{x} = \vec{0}$. Aug: $\begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

Parametrize: $s \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$. A basis is $\left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$

- $A\vec{x} = \lambda\vec{x}$: matrix multiplication to scalar multiplication
- determinant $(A - \lambda I) = 0$ or Maple for λ
- plug in each λ for nullspace of $(A - \lambda I)$ or use Maple for basis for eigenspace
- $A\vec{x} = \lambda\vec{x}$: A keeps eigenvectors \vec{x} on the same line scaled by λ , so can reason geometrically for transformations

$A := \text{Matrix}([[21/40, 3/20], [19/240, 39/40]]);$

$\text{Eigenvectors}(A); \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -6 & 6 \\ 1 & 19 \end{bmatrix}$

The eigenvector decomposition and trajectory:

$$\begin{bmatrix} \text{Owls}_k \\ \text{Rats}_k \end{bmatrix} = c_1 \left(\frac{1}{2}\right)^k \begin{bmatrix} -6 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 6 \\ 19 \end{bmatrix}$$

