Coordinates and the Unit Normal U

https://www.cse.iitb.ac.in/~cs749/spr2017/handouts/vas_surf1.pdf

coordinates for surface in \mathbb{R}^3

$$(u, v) \to x(u, v) = (x^1(u, v), x^2(u, v), x^3(u, v))$$

- coordinate curves x(u, constant) and x(constant, v)
- \vec{x}_u and \vec{x}_v are tangent vectors to the coordinate curves

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$$T_{\rho}M$$
 is $((x, y, z) - \vec{\rho}) \cdot x_u \times x_v = 0$

• The *unit normal* to the surface at a point is $U = \frac{\vec{x}_U \times \vec{x}_V}{|\vec{x}_U \times \vec{x}_V|}$ determines the tangent plane



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• coordinate curves $x(\theta, \text{constant})$ and x(constant, z)

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- coordinate curves $x(\theta, \text{constant})$ and x(constant, z)
- \vec{x}_{θ} and \vec{x}_z are tangent vectors to the coordinate curves

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- coordinate curves $x(\theta, \text{constant})$ and x(constant, z)
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$$x_{\theta} = (-r \sin \theta, r \cos \theta, 0), x_z =$$

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- coordinate curves $x(\theta, \text{constant})$ and x(constant, z)
- \vec{x}_{θ} and \vec{x}_z are tangent vectors to the coordinate curves $x_{\theta} = (-r \sin \theta, r \cos \theta, 0), x_z = (0, 0, 1)$



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$$T_{\rho}M$$
 is $((x, y, z) - \vec{p}) \cdot U = 0$ and $U = \frac{\vec{x}_{u} \times \vec{x}_{v}}{|\vec{x}_{u} \times \vec{x}_{v}|}$
 $\vec{x}_{u} \times \vec{x}_{v} = \begin{vmatrix} i & j & k \\ -r\sin\theta & r\cos\theta & 0 \\ 0 & 0 & 1 \end{vmatrix}$

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Adapted http://pi.math.cornell.edu/~henderson/courses/M4540-S12/11-DG-front+Ch1.pdf

• Choose (0,0) as an intrinsic origin.

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Adapted http://pi.math.cornell.edu/~henderson/courses/M4540-S12/11-DG-front+Ch1.pdf

- Choose (0,0) as an intrinsic origin. There is 1 geodesic that will return there, so call that the base curve
- Choose +z as a direction \perp to the base curve

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- Choose (0,0) as an intrinsic origin. There is 1 geodesic that will return there, so call that the base curve
- Choose +z as a direction \perp to the base curve
- Parameterize geodesic $\gamma(s) = (s \cos \alpha, s \sin \alpha)$.

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- Parameterize geodesic $\gamma(s) = (s \cos \alpha, s \sin \alpha)$. Then $\tan \alpha = \frac{\sin \alpha}{\cos \alpha} =$

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- Choose (0,0) as an intrinsic origin. There is 1 geodesic that will return there, so call that the base curve
- Choose +z as a direction \perp to the base curve
- Parameterize geodesic $\gamma(s) = (s \cos \alpha, s \sin \alpha)$. Then $\tan \alpha = \frac{\sin \alpha}{\cos \alpha} = \frac{s \sin \alpha}{s \cos \alpha} = \frac{z}{w}$
- Back in extrinsic coordinates, $r\theta = w, z = z$ so

$$\theta = \frac{w}{r} = \frac{s\cos\alpha}{r}$$
 and $\gamma(s) = (r\cos\frac{s\cos\alpha}{r}, r\sin\frac{s\cos\alpha}{r}, s\sin\alpha)$

Coordinates and Geodesic Curvature

coordinates for surface in \mathbb{R}^3

$$(u, v) \rightarrow x(u, v) = (x^{1}(u, v), x^{2}(u, v), x^{3}(u, v))$$

- coordinate curves x(u, constant) and x(constant, v)
- \vec{x}_u and \vec{x}_v are tangent vectors to the coordinate curves
- for regular surfaces in \mathbb{R}^3 , $T_{\rho}M$ is $((x, y, z) \vec{\rho}) \cdot U = 0$
- The *unit normal* to the surface at a point is $U = \frac{\vec{x}_u \times \vec{x}_v}{|\vec{x}_u \times \vec{x}_v|}$ determines the tangent plane
- If κ_α is the curvature vector for a curve α(t) on the surface then the *normal curvature* is the projection onto U:
 κ_n = (U · κ_α)U

The *geodesic curvature* is what is felt by the bug (in the tangent plane
$$T_{\rho}M$$
):
 $\vec{\kappa}_{q} = \vec{\kappa}_{\alpha} - \vec{\kappa}_{n}$

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Recognizing Geodesics on Cylinder using $\vec{\kappa}_{\alpha}, \vec{\kappa}_{n}, \vec{\kappa}_{g}$



Adapted http://pi.math.cornell.edu/~henderson/courses/M4540-S12/11-DG-front+Ch1.pdf

 $\vec{x}_{u} = (-sin(u), cos(u), 0), \vec{x}_{v} = (0, 0, 1).$ $U = \frac{\vec{x}_{u} \times \vec{x}_{v}}{|\vec{x}_{u} \times \vec{x}_{v}|} = (cos(u), sin(u), 0)$ $\vec{\kappa}_{\alpha} \text{ (curve's curvature vector): } \frac{T'(t)}{|\alpha'(t)|}$ $\vec{\kappa}_{n} \text{ (normal curvature): projection of } \vec{\kappa}_{\alpha} \text{ onto } U = (U \cdot \vec{\kappa}_{\alpha})U$ $\vec{\kappa}_{g} \text{ (geodesic curvature): } \vec{\kappa}_{\alpha} - \vec{\kappa}_{n}$ Ex: $\gamma(t) = (\cos t, \sin t, t)$ Calculate $\vec{\kappa}_{\gamma} = \frac{T'(t)}{|\gamma'(t)|}$ and compare with U to explain why it isn't felt by the bug

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Recognizing Geodesics on Cylinder using $\vec{\kappa}_{\alpha}, \vec{\kappa}_{n}, \vec{\kappa}_{g}$



Adapted http://pi.math.cornell.edu/~henderson/courses/M4540-S12/11-DG-front+Ch1.pdf

 $\vec{x}_{u} = (-\sin(u), \cos(u), 0), \vec{x}_{v} = (0, 0, 1).$ $U = \frac{\vec{x}_u \times \vec{x}_v}{|\vec{x}_v \times \vec{x}_v|} = (\cos(u), \sin(u), 0)$ $\vec{\kappa}_{\alpha}$ (curve's curvature vector): $\frac{T'(t)}{|\alpha'(t)|}$ $\vec{\kappa}_n$ (normal curvature): projection of $\vec{\kappa}_{\alpha}$ onto $U = (U \cdot \vec{\kappa}_{\alpha})U$ $\vec{\kappa}_{\alpha}$ (geodesic curvature): $\vec{\kappa}_{\alpha}$ - $\vec{\kappa}_{n}$ **Ex**: $\gamma(t) = (\cos t, \sin t, t)$ Calculate $\vec{\kappa}_{\gamma} = \frac{T'(t)}{|\sigma'(t)|}$ and compare with U to explain why it isn't felt by the bug $\gamma'(t) = (-\sin t, \cos t, 1)$ and $|\gamma'(t)| = \sqrt{2}$, so $T = \frac{1}{\sqrt{2}}(-\sin t, \cos t, 1)$ and $\vec{k}_{\gamma} = \frac{1}{2}(-\cos t, -\sin t, 0)$

Maple File on Geodesic and Normal Curvatures

adapted from David Henderson



 $\vec{\kappa}_{\alpha}$ pink dashed thickness 1

 $\vec{\kappa}_n$ black solid thickness 2

 $\vec{\kappa}_g$ tan dashdot style thickness 4

- The *unit normal* to the surface at a point is $U = \frac{\vec{x}_U \times \vec{x}_V}{|\vec{x}_U \times \vec{x}_V|}$
- If κ_α is the curvature vector for a curve α(t) on the surface then the *normal curvature* is the projection onto U:

$$\vec{\kappa}_n = (U \cdot \vec{\kappa}_\alpha) \dot{U}$$

• The *geodesic curvature* is what is felt by the bug (in the tangent plane $T_p M$): $\vec{\kappa}_g = \vec{\kappa}_\alpha - \vec{\kappa}_n$

Commands for Maple File on Curvatures

```
g := (x,y) -> [cos(x), sin(x), y]:
a1:=0: a2:=2*Pi: b1:=0: b2:=4:
c1 := 1: c2 := 3:
Point := 2:
f1:= (t) -> t:
f2:= (t) -> 1:
```

```
g := (x,y) -> [cos(x), sin(x), y]:
al:=0: a2:=2*Pi: b1:=0: b2:=4:
c1 := 1: c2 := 3:
Point := 2:
f1:= (t) -> t:
f2:= (t) -> sin(t):
```

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Commands for Maple File on Curvatures

```
g := (x,y) -> [cos(x), sin(x), y]:
a1:=0: a2:=2*Pi: b1:=0: b2:=4:
c1 := 1: c2 := 20:
Point := 2:
f1:= (t) -> t*cos(Pi/16):
f2:= (t) -> t*sin(Pi/16):
```

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Commands for Maple File on Curvatures

```
g := (x,y) -> [cos(x), sin(x), y]:
a1:=0: a2:=2*Pi: b1:=0: b2:=4:
c1 := 1: c2 := 20:
Point := 2:
f1:= (t) -> t*cos(Pi/16):
f2:= (t) -> t*sin(Pi/16):
```



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