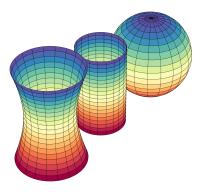
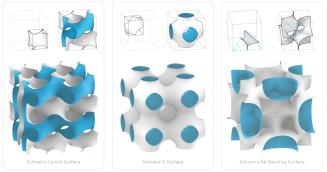
1. According to the reading, one of the greatest achievements of the theory of surfaces was:

- a) analytic geometry
- b) Gauss-Bonnet theorem
- c) classification of surfaces
- d) discovering surfaces that stretch the imagination
- e) none of the above



- 2. How long have surfaces been studied?
 - a) In a very short time period during Gauss' lifetime
 - b) From at least the Greeks until the 1800s
 - c) From at least the Greeks until the 1900s
 - d) From at least the Greeks until now
 - e) none of the above



https://wewanttolearn.files.wordpress.com/2019/01/tpms-cover-1.jpg?w=1200

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- 3. According to the reading, what does the Gaussian curvature measure?
 - a) the deviance of a curve on the surface from being a geodesic
 - b) the deviance of the surface from being a plane at each point
 - c) the deviance of the surface from being a round earth at each point
 - d) how curvy Gauss' ear was
 - e) none of the above

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4. For curves we learned that curvature and torsion determine the curve up to rigid motion. What are the corresponding features that determine a surface up to rigid motion?

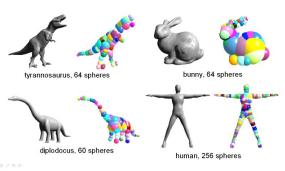
- a) two parameters curvature and torsion
- b) one parameter, the Gaussian curvature
- c) six coefficients of parametric equations called the first and second fundamental forms, local invariants that are functions of arc length
- d) eleven dimensions from string theory
- e) need an infinite amount of information to obtain a surface



5. Is is possible to win an Academy Award (Oscars) for working on surfaces?

- a) yes and it has already happened
- b) yes but no one has yet
- c) no

Results



http://research.microsoft.com/en-us/um/people/johnsny/images/sphapprox_big.jpg > 🛓 🔗 🔍

- 6. According to the reading, surfaces can be represented using
 - a) 1–8 below
 - b) all but 1 and 8
 - c) other
 - 1) if it is surface of revolutions, then by the revolutions that form it
 - 2) analysis
 - 3) algebra
 - 4) geometry
 - 5) polygon meshes
 - 6) physical models and sculptures
 - 7) computer animations
 - 8) soap bubbles

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Cones and Cylinders

Maple visualization of rolling a geodesic-cone and cylinder

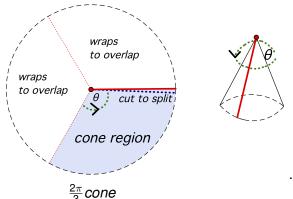


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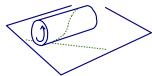
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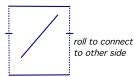
Cones and Cylinders

Maple visualization of rolling a geodesic—cone and cylinder 0 < cone angle $< 2\pi$ variable cone



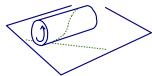
We can vary the angle by changing the cone region before we wrap the rest around (it doesn't have to fit evenly into 2π)

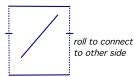






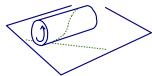
- symmetry and our feet
- rolling arguments (covering arguments in general)
- 1. Geodesic ever intersect itself?

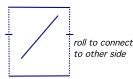






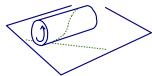
- symmetry and our feet
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- 1. Geodesic ever intersect itself? Yes. horizontal circle
- 2. Shapes?

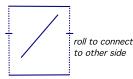






- symmetry and our feet
- rolling arguments (covering arguments in general)
- 1. Geodesic ever intersect itself? Yes. horizontal circle
- 2. Shapes? vertical lines, horizontal circles, helices (constant angle is made with the z-axis because it is a straight line on the unrolled cylinder)
- 3. Straight always shortest distance?



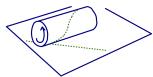


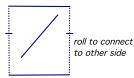


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- 3. Straight always shortest distance? No.

or circle backside

4. Shortest distance always straight?

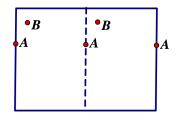






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- 1. Geodesic ever intersect itself? Yes. horizontal circle
- 2. Shapes? vertical lines, horizontal circles, helices (constant angle is made with the z-axis because it is a straight line on the unrolled cylinder)
- 3. Straight always shortest distance? No. C or circle backside
- 4. Shortest distance always straight? Yes. shortest on cylinder is shortest on covering & hence intrinsically straight on both5. How many geodesics join 2 points?

(Intrinsically Straight) Geodesics on a Cylinder 5. How many geodesics join 2 points? A 2-sheeted covering:



- Fold a paper in half vertically so you have 2 equal regions
- Label point A on each edge at the same height (3 As)
- Choose Bs not on the same vertical or horizontal line as A
- Draw a line between every A and every B. Marker is best.
- Roll the sheet up so As match & examine the geodesics

5. How many geodesics join 2 points?

horizontal points: 1 (they are part of the same geodesic circle, aside from # times it overlaps or goes around front or back)

non-horizontal points—keep adding sheets to the covering: ∞ (countably)

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Applications of unwrapping: Surface Area of a Cylinder

intrinsic

travel on a straight path until we come back around to where we started and measure that distance

compute extrinsic surface area using the covering

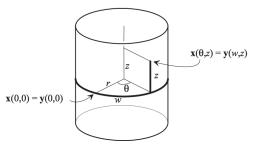
Applications of unwrapping: Surface Area of a Cylinder

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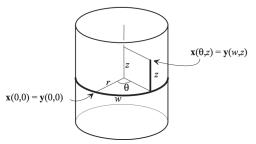
- compute extrinsic surface area using the covering
- later we will compute surface area more generally using the first fundamental form





http://pi.math.cornell.edu/~henderson/courses/M4540-S12/11-DG-front+Ch1.pdf

- Choose (0,0,0), 3 \perp axes, +z as a cylinder height axis
- Let θ be the angle traveled from the origin in the xy plane

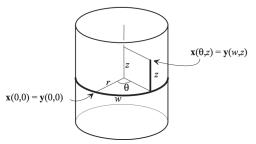


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Extrinsic coordinates : $x(\theta, z) = (rcos(\theta), rsin(\theta), z)$. Equation of cylinder: $x^2 + y^2 = r^2$ in \mathbb{R}^3 Compute T_p cylinder and U

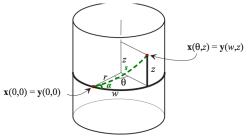
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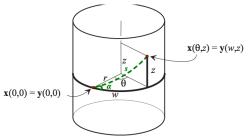
Extrinsic coordinates : $x(\theta, z) = (rcos(\theta), rsin(\theta), z)$. Equation of cylinder: $x^2 + y^2 = r^2$ in \mathbb{R}^3 Compute T_p cylinder and UProblem: Bug no awareness of 3-space



Adapted http://pi.math.cornell.edu/~henderson/courses/M4540-S12/11-DG-front+Chl.pdf
 Choose (0,0) as an intrinsic origin.

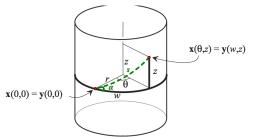
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Adapted http://pi.math.cornell.edu/~henderson/courses/M4540-S12/11-DG-front+Ch1.pdf

• Choose (0,0) as an intrinsic origin. There is 1 geodesic that will return there, so call that the base curve



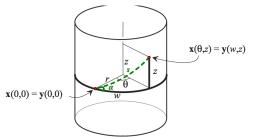
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that will return there, so call that the base curve

• Choose +z as a direction \perp to the base curve

Geodesic rectangular coordinates: y(w, z) = walk w units along base curve and turn 90° to positive z and travel z units.



Adapted http://pi.math.cornell.edu/~henderson/courses/M4540-S12/11-DG-front+Ch1.pdf

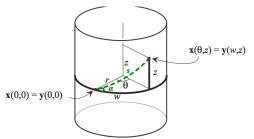
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Geodesic polar coordinates: $y(\alpha, s) = \text{turn } \alpha$ degrees from the base curve and walk *s* units along that geodesic Parameterize $\gamma(s)$ and use *s*, α , *w*, *z* to write equation.



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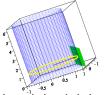
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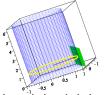
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Curvatures on Surfaces in Extrinsic Coordinates



- Cylinder: $\mathbf{x} (u, v) = (cos(u), sin(u), v)$
- \vec{x}_u and \vec{x}_v are tangent vectors
- The *unit normal* to the surface at a point is $U = \frac{\vec{x}_U \times \vec{x}_V}{|\vec{x}_U \times \vec{x}_V|}$ determines the tangent plane

Curvatures on Surfaces in Extrinsic Coordinates

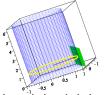


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- The *unit normal* to the surface at a point is $U = \frac{\vec{x}_U \times \vec{x}_V}{|\vec{x}_U \times \vec{x}_V|}$ determines the tangent plane
- If κ_α is the curvature vector for a curve α(t) on the surface then the *normal curvature* is the projection onto U:

$$\vec{\kappa}_n = (U \cdot \vec{\kappa}_\alpha) \dot{U}$$

The *geodesic curvature* is what is felt by the bug (in the tangent plane T_pM):

Curvatures on Surfaces in Extrinsic Coordinates



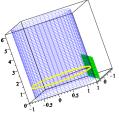
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$$\vec{\kappa}_n = (U \cdot \vec{\kappa}_\alpha) U$$

• The *geodesic curvature* is what is felt by the bug (in the tangent plane $T_p M$): $\vec{\kappa}_q = \vec{\kappa}_{\alpha} - \vec{\kappa}_{\beta}$

Maple File on Geodesic and Normal Curvatures

adapted from David Henderson



 $\vec{\kappa}_{\alpha}$ pink dashed thickness 1

 $\vec{\kappa}_n$ black solid thickness 2

 $\vec{\kappa}_g$ tan dashdot style thickness 4

- The *unit normal* to the surface at a point is $U = \frac{\vec{x}_U \times \vec{x}_V}{|\vec{x}_U \times \vec{x}_V|}$
- If κ_α is the curvature vector for a curve α(t) on the surface then the *normal curvature* is the projection onto U:

$$\vec{\kappa}_n = (U \cdot \vec{\kappa}_\alpha) U$$

• The *geodesic curvature* is what is felt by the bug (in the tangent plane $T_p M$): $\vec{\kappa}_q = \vec{\kappa}_\alpha - \vec{\kappa}_p$

Commands for Maple File on Curvatures

```
g := (x,y) -> [cos(x), sin(x), y]:
a1:=0: a2:=2*Pi: b1:=0: b2:=2*Pi:
c1 := 1: c2 := 3*Pi:
Point := 2:
f1:= (t) -> t:
f2:= (t) -> 1:
```

```
g := (x,y) -> [cos(x), sin(x), y]:
al:=0: a2:=2*Pi: b1:=0: b2:=Pi:
c1 := 1: c2 := 3:
Point := 2:
f1:= (t) -> t:
f2:= (t) -> sin(t):
```

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