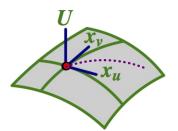
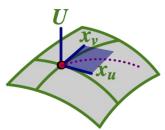
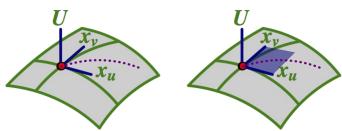


• Regular surface $M = \mathbf{x}(u, v)$, where $\vec{x}_u \times \vec{x}_v \neq 0$, and u(t) & v(t) give curve $\alpha(t)$. Then \vec{x}_u, \vec{x}_v form basis for T_pM and $\alpha'(t) =$

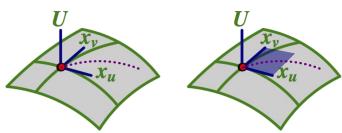




• Regular surface $M = \mathbf{x}(u, v)$, where $\vec{x}_u \times \vec{x}_v \neq 0$, and u(t) & v(t) give curve $\alpha(t)$. Then \vec{x}_u, \vec{x}_v form basis for T_pM and $\alpha'(t) = \vec{x}_u \frac{du}{dt} + \vec{x}_v \frac{dv}{dt}$



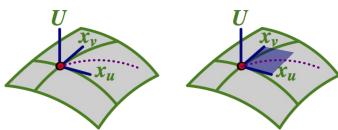
• Regular surface $M = \mathbf{x}(u, v)$, where $\vec{x}_u \times \vec{x}_v \neq 0$, and u(t) & v(t) give curve $\alpha(t)$. Then \vec{x}_u, \vec{x}_v form basis for T_pM and $\alpha'(t) = \vec{x}_u \frac{du}{dt} + \vec{x}_v \frac{dv}{dt}$ $(\frac{ds}{dt})^2 = |\alpha'(t)|^2 = \alpha'(t) \cdot \alpha'(t) =$



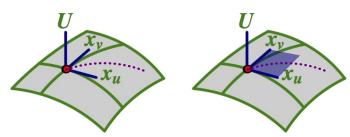
• Regular surface $M = \mathbf{x}(u, v)$, where $\vec{x}_u \times \vec{x}_v \neq 0$, and u(t)& v(t) give curve $\alpha(t)$. Then $\vec{x}_{tt}, \vec{x}_{v}$ form basis for $T_{D}M$ and $\alpha'(t) = \vec{x_u} \frac{du}{dt} + \vec{x_v} \frac{dv}{dt}$

$$(\frac{ds}{dt})^2 = |\alpha'(t)|^2 = \alpha'(t) \cdot \alpha'(t) = (\vec{x_u} \frac{du}{dt} + \vec{x_v} \frac{dv}{dt}) \cdot (\vec{x_u} \frac{du}{dt} + \vec{x_v} \frac{dv}{dt})$$





• Regular surface $M = \mathbf{x}(u, v)$, where $\vec{x}_u \times \vec{x}_v \neq 0$, and u(t) & v(t) give curve $\alpha(t)$. Then \vec{x}_u, \vec{x}_v form basis for $T_p M$ and $\alpha'(t) = \vec{x_u} \frac{du}{dt} + \vec{x_v} \frac{dv}{dt}$ $(\frac{ds}{dt})^2 = |\alpha'(t)|^2 = \alpha'(t) \cdot \alpha'(t) = (\vec{x_u} \frac{du}{dt} + \vec{x_v} \frac{dv}{dt}) \cdot (\vec{x_u} \frac{du}{dt} + \vec{x_v} \frac{dv}{dt})$ $= \vec{x_u} \cdot \vec{x_u} (\frac{du}{dt})^2 + 2\vec{x_u} \cdot \vec{x_v} \frac{du}{dt} \frac{dv}{dt} + \vec{x_v} \cdot \vec{x_v} (\frac{dv}{dt})^2$



- Regular surface $M = \mathbf{x}(u, v)$, where $\vec{x}_u \times \vec{x}_v \neq 0$, and u(t) & v(t) give curve $\alpha(t)$. Then \vec{x}_u, \vec{x}_v form basis for T_pM and $\alpha'(t) = \vec{x}_u \frac{du}{dt} + \vec{x}_v \frac{dv}{dt}$ $(\frac{ds}{dt})^2 = |\alpha'(t)|^2 = \alpha'(t) \cdot \alpha'(t) = (\vec{x}_u \frac{du}{dt} + \vec{x}_v \frac{dv}{dt}) \cdot (\vec{x}_u \frac{du}{dt} + \vec{x}_v \frac{dv}{dt})$ $= \vec{x}_u \cdot \vec{x}_u (\frac{du}{dt})^2 + 2\vec{x}_u \cdot \vec{x}_v \frac{du}{dt} \frac{dv}{dt} + \vec{x}_v \cdot \vec{x}_v (\frac{dv}{dt})^2$ $= E(\frac{du}{dt})^2 + 2F\frac{du}{dt}\frac{dv}{dt} + G(\frac{dv}{dt})^2$ $ds^2 = g_{11}(du^1)^2 + 2g_{12}du^1du^2 + g_{22}(du^2)^2 = \sum_{i,j} g_{ij}du^jdu^j$
- $\mathbf{x}(u, v) = (u, v, 0)$ compared to $\mathbf{x}(u, v) = (u \cos v, u \sin v, u)$

- Matrix representation: $g_{ij} = \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} = \begin{bmatrix} E & F \\ F & G \end{bmatrix}$
- g_{ij} determines dot products of tangent vectors \vec{w}_1 , \vec{w}_2 in T_pM

$$\{ec x_u,ec x_v\}$$
 is a basis: $ec w_1=aec x_u+bec x_v$, $ec w_2=cec x_u+dec x_v$ $ec w_1\cdotec w_2\stackrel{
m foil}=$

- Matrix representation: $g_{ij} = \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} = \begin{bmatrix} E & F \\ F & G \end{bmatrix}$
- g_{ij} determines dot products of tangent vectors \vec{w}_1 , \vec{w}_2 in $T_D M$

$$\{\vec{x}_u, \vec{x_v}\}\$$
 is a basis: $\vec{w}_1 = a\vec{x_u} + b\vec{x_v}$, $\vec{w}_2 = c\vec{x_u} + d\vec{x_v}$
 $\vec{w}_1 \cdot \vec{w}_2 \stackrel{\text{foil}}{=} ac\vec{x}_u \cdot \vec{x}_u + (ad + bc)\vec{x}_u \cdot \vec{x}_v + bd\vec{x}_v \cdot \vec{x}_v$
 $= acE + (ad + bc)F + bdG$

- Matrix representation: $g_{ij} = \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} = \begin{bmatrix} E & F \\ F & G \end{bmatrix}$
- g_{ij} determines dot products of tangent vectors \vec{w}_1 , \vec{w}_2 in T_pM

$$\begin{aligned} \{\vec{x}_{u}, \vec{x_{v}}\} & \text{ is a basis: } \vec{w}_{1} = a\vec{x_{u}} + b\vec{x_{v}} \text{ , } \vec{w}_{2} = c\vec{x_{u}} + d\vec{x_{v}} \\ \vec{w}_{1} \cdot \vec{w}_{2} & \stackrel{\text{foil}}{=} ac\vec{x}_{u} \cdot \vec{x}_{u} + (ad + bc)\vec{x_{u}} \cdot \vec{x_{v}} + bd\vec{x_{v}} \cdot \vec{x_{v}} \\ & = acE + (ad + bc)F + bdG = a(cE + dF) + b(cF + dG) \\ & = \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} cE + dF \\ cF + dG \end{bmatrix} \end{aligned}$$

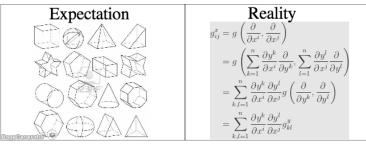
- Matrix representation: $g_{ij} = \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} = \begin{bmatrix} E & F \\ F & G \end{bmatrix}$
- g_{ij} determines dot products of tangent vectors \vec{w}_1 , \vec{w}_2 in T_pM

$$\begin{aligned} \{\vec{x}_u, \vec{x_v}\} & \text{ is a basis: } \vec{w}_1 = a\vec{x_u} + b\vec{x_v} \text{ , } \vec{w}_2 = c\vec{x_u} + d\vec{x_v} \\ \vec{w}_1 \cdot \vec{w}_2 & \stackrel{\text{foil}}{=} ac\vec{x}_u \cdot \vec{x}_u + (ad + bc)\vec{x}_u \cdot \vec{x}_v + bd\vec{x}_v \cdot \vec{x}_v \\ & = acE + (ad + bc)F + bdG = a(cE + dF) + b(cF + dG) \\ & = \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} cE + dF \\ cF + dG \end{bmatrix} \\ & = \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} E & F \\ F & G \end{bmatrix} \begin{bmatrix} c \\ d \end{bmatrix}$$

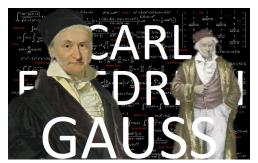
- Matrix representation: $g_{ij} = \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} = \begin{bmatrix} E & F \\ F & G \end{bmatrix}$
- g_{ij} determines dot products of tangent vectors \vec{w}_1 , \vec{w}_2 in T_pM

$$\begin{aligned} \{\vec{x}_{U}, \vec{x_{V}}\} & \text{ is a basis: } \vec{w}_{1} = a\vec{x_{U}} + b\vec{x_{V}} \text{ , } \vec{w}_{2} = c\vec{x_{U}} + d\vec{x_{V}} \\ \vec{w}_{1} \cdot \vec{w}_{2} & \stackrel{\text{foil}}{=} ac\vec{x}_{U} \cdot \vec{x}_{U} + (ad + bc)\vec{x_{U}} \cdot \vec{x}_{V} + bd\vec{x}_{V} \cdot \vec{x}_{V} \\ & = acE + (ad + bc)F + bdG = a(cE + dF) + b(cF + dG) \\ & = \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} cE + dF \\ cF + dG \end{bmatrix} \\ & = \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} E & F \\ F & G \end{bmatrix} \begin{bmatrix} c \\ d \end{bmatrix} \\ & = \vec{w}_{1} \cdot \vec{w}_{2} = |\vec{w}_{1}||\vec{w}_{2}|\cos\theta \end{aligned}$$

E, F, G play important roles in many intrinsic properties of a surface like length $(\frac{ds}{dt})^2$, area (det) and angles (above)

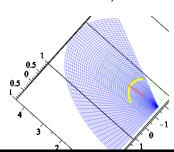


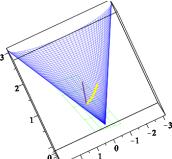
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http://vignettel.wikia.nocookie.net/epicrapbattlesofhistory/images/8/83/Pizap. com14239077419801.jpg

- Maple file coneandplaneforms.mw new plane $[\sqrt{2}x\cos(\frac{y}{\sqrt{2}}), \sqrt{2}x\sin(\frac{y}{\sqrt{2}}), 0]$ that is isometric to the cone $[x \cos(y), x \sin(y), x]$
- longitude and latitude on the new plane
- first fundamental form of the new plane and cone
- using secant to write the geodesic between the points (1,0,1) and (0,1,1) on the cone (i.e. the point x=1 and y=0 and the point $x=1, y=\frac{\pi}{2}$ (see p. 247–248 for more information)

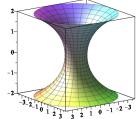


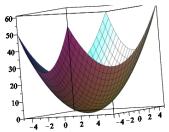


For homework today you were to read section 2.1. Write down examples of surfaces for each type of parametrization.

- surface of revolution $x(u, v) = (g(u), h(u) \cos v, h(u) \sin v)$ from a planar curve $\alpha(u) = (g(u), h(u), 0)$
- ruled surface $x(u, v) = \beta(u) + v\delta(u)$, where β and δ are curves and x(u, v) is lines emanating from the directrix β going in the direction of δ
- Monge patch x(u, v) = (u, v, f(u, v))
- geographical coordinates $x(u, v) = (R \cos u \cos v, R \sin u \cos v, R \sin v)$







http://www.funnyism.com/i/memefactory/how-do-you-make-a-catenoid-pull-its-tail