

Work quickly and carefully, following directions closely. Answer all questions completely.

FOR ALL PROBLEMS: Define P , Q , R , and S to be the four digits in your given number.

$$P = \underline{\quad}, \quad Q = \underline{\quad}, \quad R = \underline{\quad}, \quad S = \underline{\quad}.$$

§I. TRUE and/or FALSE. Circle your answer. There are 3 questions at 2 points each.

- TRUE or FALSE: The origin is the only equilibrium point for any linear system.
- TRUE or FALSE: The x - and y -nullclines of a nonlinear system cannot intersect.
- TRUE or FALSE: The value of the improper integral $\int_0^{\infty} \delta(t-R)e^{-t} dt$ (where R is your number) is e^{-R} .

§II. MULTIPLE CHOICE. Circle your answer. There are 2 question at 5 points each.

- The *eigenvalues* for the system $\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 1 & P \\ 0 & Q \end{bmatrix}$ (where P and Q are your numbers) are $\lambda =$
 - 1 and 0
 - P and Q
 - P and 0
 - 1 and Q
- Linearizing the differential equation $\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} x^2 + \sin(x) \\ y - \sin(xy) \end{bmatrix}$ at the origin gives $\frac{d}{dt}\vec{V} = \mathbf{A} \cdot \vec{V}$ with \mathbf{A} equal to:
 - $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$
 - $\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$
 - $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

§III. MATCHING. Four functions $y(t)$ and twelve functions $Y(s)$ are given below. For each function $y(t)$, match it with its Laplace transform $Y(s)$. There are 4 matches at 3 points each.

$$y = e^{2t} \cos(2t) \quad Y = \boxed{\quad}$$

$$y = e^{2t} - e^{-2t} \quad Y = \boxed{\quad}$$

$$y = \sin(t - \pi) \quad Y = \boxed{\quad}$$

$$y = u(t-2) \cdot e^{3t-6} \quad Y = \boxed{\quad}$$

I. $Y = \frac{4}{s^2 - 4}$

II. $Y = \frac{4}{s^2 + 4}$

III. $Y = \frac{2}{s^2 + 4}$

IV. $Y = \frac{2s}{s^2 + 4}$

V. $Y = \frac{s}{s^2 - 4}$

VI. $Y = \frac{-1}{s^2 + 1}$

VII. $Y = \frac{s}{s^2 + 4}$

VIII. $Y = \frac{e^{-2s}}{s+3}$

IX. $Y = \frac{e^{-2s}}{s-3}$

X. $Y = \frac{s}{s^2 - 4s + 8}$

XI. $Y = \frac{s-2}{s^2 - 4s + 8}$

XII. $Y = \frac{e^{-\pi s}}{s^2 + 1}$

Go on to the next page.

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§IV. PROBLEMS. *You must show your work to receive credit.* There are 4 problems at 20 points each.

1. The linear differential system $\frac{d}{dt}\vec{Y} = \mathbf{A} \cdot \vec{Y}$ has eigenvalues $\lambda_1 = (-1)^P$ and $\lambda_2 = (-\frac{1}{2})^Q$ (where P and Q are your numbers). Determine what type of equilibrium the origin is.

2. Consider the differential equation $x''(t) + x'(t) + Rx(t) = 0$ with $x(0) = 1$ and $x'(0) = 1$. (R is your number.)

- (a) Convert the differential equation to a system of two variables x and v .
- (b) Determine the type of equilibrium of the system at the origin.



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3. Find the inverse Laplace transform of the function $F(s) = e^{-Qs} \cdot \frac{3!}{s^4}$ where Q is your number.

4. Use Laplace transforms to solve the initial value problem $\frac{d^4x}{dt^4} - x = 4$ with $x'''(0) = x''(0) = x'(0) = x(0) = 0$.



EC—TEST JEOPARDY: The answer was “Twelve sided geometric shape,” not “Giant blood-thirsty dinosaur.” What was the question?