## Finding an "eigen-basis" to diagonalize a matrix

- 1. Set  $A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ . Find  $p(\lambda)$  by evaluating  $|A \lambda I| = \begin{vmatrix} 1-\lambda & 0 & 0 \\ 1 & -\lambda & 0 \\ 0 & 0 & 1-\lambda \end{vmatrix} = \lambda^3 2\lambda^2 + \lambda$ =  $\lambda (\lambda - 1)^2$ . Now the eigenvalues are the roots of  $p(\lambda)$ , so  $\Lambda_A = \{0, 1\}$ . To find eigenvectors that span  $\mathfrak{N}_{\lambda}$ , look at  $\mathfrak{N}(A - \lambda I)$ .
  - (a) First use  $\lambda = 0$ . Find the nullspace associated with  $A 0I = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$  by solving the system  $\begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_1 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ . So  $x_1 = x_3 = 0$  and  $x_2$  is arbitrary. This implies that  $\mathfrak{N}_0 = \langle \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \rangle$ .
  - (b) Now use  $\lambda = 1$ . Find the nullspace of  $A 1I = \begin{bmatrix} 0 & 0 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  by solving the system  $\begin{bmatrix} 0 & 0 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ . So  $x_1 = x_2$  and  $x_3$  is arbitrary. This implies that  $\mathfrak{N}_1 = \langle \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \rangle$ .

Hence an eigenbasis for  $\mathbb{R}^3$  w.r.t. A is  $\left\{ \begin{bmatrix} 0\\1\\0 \end{bmatrix}, \begin{bmatrix} 1\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\0\\0 \end{bmatrix} \right\}$ . With the vectors in this order, we have  $P = \begin{bmatrix} 0 & 1 & 0\\1 & 1 & 0\\0 & 0 & 1 \end{bmatrix}$ . Then  $P^{-1}AP$  must equal  $\begin{bmatrix} 0 & 0 & 0\\0 & 1 & 0\\0 & 0 & 1 \end{bmatrix}$ .

- 2. Set  $B = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 1 & 2 \\ 1 & 0 & 1 \end{bmatrix}$ . Find  $p(\lambda)$  by evaluating  $|A \lambda I| = \lambda^3 3\lambda^2 = \lambda^2 (\lambda 3)$ . The eigenvalues are the roots of  $p(\lambda)$ , so  $\Lambda_B = \{0, 3\}$ .
  - (a) First use  $\lambda = 0$ . Find the nullspace associated with  $B 0I = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 1 & 2 \\ 1 & 0 & 1 \end{bmatrix}$  by solving the system  $\begin{bmatrix} 1 & 1 & 2 \\ 1 & 1 & 2 \\ 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 + 2x_3 \\ x_1 + x_2 + 2x_3 \\ x_1 + x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ . So  $x_2 = -x_3 = x_1$  and  $x_1$  is arbitrary. This implies that  $\mathfrak{N}_0 = \langle \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \rangle$ .
  - (b) Now use  $\lambda = 3$ . Find the nullspace of  $B 3I = \begin{bmatrix} -2 & 1 & 2 \\ 1 & -2 & 2 \\ 1 & 0 & -2 \end{bmatrix}$  by solving the system  $\begin{bmatrix} -2 & 1 & 2 \\ 1 & -2 & 2 \\ 1 & 0 & -2 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2x_1 + x_2 + 2x_3 \\ x_1 2x_2 + 2x_3 \\ x_1 2x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ . So  $x_1 = x_2 = 2x_3$  and  $x_3$  is arbitrary. This implies that  $\mathfrak{N}_3 = \langle \begin{bmatrix} 2 \\ 2 \\ 1 \\ 2 \\ 1 \end{pmatrix} \rangle$ .

We do not have a full set of eigenvectors to make a basis. Therefore, there is no nonsingular matrix P that can be used to give  $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{bmatrix}$  from  $P^{-1}BP$ . In this case, B is called a *deficient* matrix.

For  $A, B \in L(X, X)$  where  $\dim(X) = n$ , the critical observation is that for A, we have that  $\sum_{\lambda \in \Lambda_A} \dim(\mathfrak{N}_{\lambda}) = n$ , but for B, we see that  $\sum_{\lambda \in \Lambda_B} \dim(\mathfrak{N}_{\lambda}) < n$ .

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