

Heaps denote finitely partitioned forests

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References

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- ML-like languages allows **generation** of references.

- A **reference** is a memory address storing a value. It may be read or updated.
- ML-like languages allows **generation** of references.
- ML provides **general** references; they may store values of any type, even functions and thunks.
- Sometimes we study languages that allow only **ground** references, i.e. references to integers or booleans.
- Sometimes we study languages with **full ground** references, i.e. references to integers and also references to references to integers, but not references to code.

Some denotational models of higher-order languages with references:

- Game semantics of full ground references, using strong nominal sets (Laird; Murawski and Tzevelekos)
- Game semantics of “good” general references, using strong nominal sets (Laird; Murawski and Tzevelekos)
- Kripke semantics of full ground references, using ends and coends (Kammar, Levy, Moss and Staton)

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This talk is just about a first-order language with full ground references.

I hope this will eventually yield an improved account of these higher-order models.

One reference type

We consider a first order language—no function types. The type syntax is.

$$A ::= 0 \mid A + A \mid 1 \mid A \times A \mid \text{Ref} \mid X \mid \text{rec } X. A$$

A reference (memory location) has type Ref and stores a value of type

$$D \stackrel{\text{def}}{=} \text{bool} \times \text{Ref} \times \text{Ref} + \text{nat}$$

Fancy version

Several sorts of references, e.g. red and blue.

A red reference has type Ref_{red} and stores a value of type D_{red} .

A blue reference has type Ref_{blue} and stores a value of type D_{blue} .

The calculus is “fine-grain call-by-value”.

The judgements are

- $w, \Gamma \vdash^v V : A$ for values
- $w, \Gamma \vdash^c M : A$ for computations.

Here w is a *world*, which is a number—the size of the memory.
Or a finite sequence of sorts, if there are several sorts.

Here is the term syntax:

$$\begin{aligned} V, W & ::= x \mid 1 \mid \text{in}_i V \mid \langle \rangle \mid \langle V, W \rangle \mid \text{roll } V \\ M, N & ::= \text{return } V \mid M \text{ to } x. M \\ & \quad \mid \text{match } V \text{ as } \dots \\ & \quad \mid \text{if } V = W \text{ then } M \text{ else } N \\ & \quad \mid V := W. M \\ & \quad \mid \text{read } V \text{ as } x. M \\ & \quad \mid \text{new } x := \overrightarrow{V}. M \end{aligned}$$

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$$w, M \Downarrow w', V$$

where $w' \sqsubseteq w$ and $w' \vdash^v V : A$.

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The observational preorder is obtained from programs of boolean type.

Reference non-use and swap:

$$M \simeq \text{new } x := \overrightarrow{V}. M$$

$$\text{new } x := \overrightarrow{V}, y := W, y' := W', z := \overrightarrow{V'}. M$$

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Fine-grain call-by-value is modelled by a **distributive Freyd category**.

- A category \mathcal{C}
- A category \mathcal{K} with the same objects as \mathcal{C}
- An identity-on-objects functor $\iota : \mathcal{C} \rightarrow \mathcal{D}$
- Extra structure for the product and sum types.

A type denotes an object of \mathcal{C} .

A value $\Gamma \vdash^v V : A$ denotes a \mathcal{C} -morphism $[[\Gamma]] \rightarrow [[A]]$.

A computation $\Gamma \vdash^c M : A$ denotes a \mathcal{K} -morphism $[[\Gamma]] \rightarrow [[A]]$.

More categories are required for terms $w, \Gamma \vdash^v V : A$ and $w, \Gamma \vdash^c M : A$.

Basic semantics of a computation (Levy 2002)

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Given

- some local cells \vec{l}
- an environment ρ for Γ , using cells in w, \vec{l}
- a state s for w, \vec{l}

the computation terminates with

- some more local cells \vec{l}'
- a value v of type A , using cells in w, \vec{l}, \vec{l}'
- a state s' for w, \vec{l}, \vec{l}'

In summary $\llbracket M \rrbracket : \vec{l}, \rho, s \mapsto \vec{l}', v, s'$.

In the basic model, a computation denotes a function:

$$\llbracket M \rrbracket: \vec{T}, \rho, s \mapsto \vec{T}', v, s'$$

In the strong nominal set model and the end/coend model

- functions are **identified** up to reference non-use and swap
- functions are **constrained** to propagate reference non-use and swap.

Aim

To reformulate the equivariant model in an explicit way:

- the homset $\mathcal{K}(A, B)$ will be of the form $\prod_{x \in X} Y(x)$
“A computation denotes a function”.
- elements of X and $Y(x)$ will not be equivalence classes.

Template sets

Let **Inj** be the category of finite sets and injections.

Then **Fam**(**Inj**^{op}) is the category of **template sets**.

(Equivalent to strong nominal sets.)

A type denotes a template set, i.e. a family of finite sets.

Templates for $\text{bool} \times \text{Ref} \times \text{Ref} + \text{nat}$

`inl` $\langle b, -_0, -_0 \rangle$ ($b \in \mathbb{B}$) Arity = 1

`inl` $\langle b, -_0, -_1 \rangle$ ($b \in \mathbb{B}$) Arity = 2

`inr` n ($n \in \mathbb{N}$) Arity = 0

The template set is indexed by $\mathbb{B} + \mathbb{B} + \mathbb{N}$.

Semantics of a value $\Gamma \vdash^v V : A$

Let $\llbracket \Gamma \rrbracket = (X_i)_{i \in I}$ and $\llbracket A \rrbracket = (Y_j)_{j \in J}$.

Then V denotes a map of template sets $(X_i)_{i \in I} \rightarrow (Y_j)_{j \in J}$.

For every template i , we obtain

- a template j
- a map of references $Y_j \rightarrow X_i$.

Reason: every reference in $V[W_x/x]_{x \in \Gamma}$ arises from one in $(W_x)_{x \in \Gamma}$.

Product of template sets A and B

If $\llbracket A \rrbracket = (X_i)_{i \in I}$ and $\llbracket B \rrbracket = (Y_j)_{j \in J}$,

a template for $A \times B$ consists of

- a template i for A
- a template j for B
- a **matching**—i.e. equivalence relation R on $A + B$, discrete on each component

and the arity of (i, j, R) is $A + B / R$.

Indistinguishable inputs to $x : \text{bool} + \text{Ref} \times \text{Ref} \vdash^c M : A$

l_0, l_1, l_2, l_3

$x \mapsto \text{inr } \langle l_1, l_2 \rangle$

$l_0 := \text{inr } 17$

$l_1 := \text{inl } \langle \text{true}, l_1, l_1 \rangle$

$l_2 := \text{inl } \langle \text{false}, l_0, l_2 \rangle$

l_0, l_1, l_2, l_3, l_4

$x \mapsto \text{inr } \langle l_4, l_0 \rangle$

$l_0 := \text{inl } \langle \text{false}, l_2, l_0 \rangle$

$l_1 := \text{inl } \langle \text{false}, l_0, l_0 \rangle$

$l_2 := \text{inr } 17$

$l_3 := \text{inr } 5$

$l_4 := \text{inl } \text{true}, l_4, l_4$

Heap = finitely partitioned tree

A reference stores a value of type D , and $\llbracket D \rrbracket = (C_k)_{k \in K}$.

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For each $c_0 \in C_{r(x)}$ we need a template $r(x, c_0) \in K$

For each $c_1 \in C_{r(x, c_0)}$ we need a template $r(x, c_0, c_1) \in K$

Etc.

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In summary, we need a (non-well-founded) forest with X_i roots, where each node is labelled with $k \in K$ and has C_k children.

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Etc.

In summary, we need a (non-well-founded) forest with X_i roots, where each node is labelled with $k \in K$ and has C_k children.

This gives a family of finite sets, one at each node.

Each node is a reference. Reference equality is observable, so the nodes are partitioned into finitely many parts.

In summary, a heap is a **finitely partitioned forest**.

Summary

A computation $\Gamma \vdash^c M : A$ denotes a function taking a template (environment) and finitely partitioned forest (heap) to a template (value) and finitely partitioned forest (heap).

No equivariance constraint or identification are used, as a finitely partitioned forest gives the observable data about a heap and does not mention unreachable references or reference order.

We thus obtain a Freyd category on **Fam(Inj^{op})**.